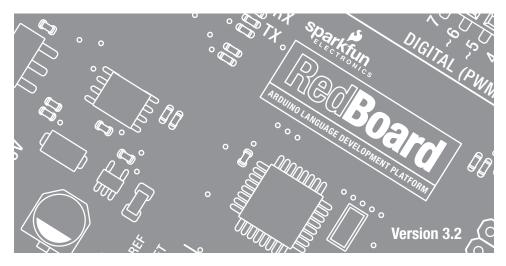




### Your guide to the SparkFun Inventor's Kit for the SparkFun RedBoard





### Welcome to the SparkFun Inventor's Guide

The SparkFun Inventor's Guide is your map for navigating the waters of beginning embedded electronics. This booklet contains all the information you will need to explore the 16 circuits of the SparkFun Inventor's Kit for Educators. At the center of this manual is one core philosophy - that anyone can (and should) play around with electronics. When you're done with this guide, you'll have the know-how to start creating your own projects and experiments. Now enough talking - let's get inventing!

#### www.sparkfun.com



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### What is the RedBoard platform?



### **The DIY Revolution**

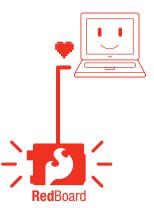
We live in a unique time where we have access to resources that allow us to create our own solutions and inventions. The DIY revolution is composed of hobbyists, tinkerers and inventors who would rather craft their own projects than let someone do it for them.

#### www.sparkfun.com

### A Computer for the Physical World

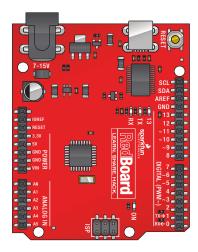
The RedBoard in your hand (or on your desk) is your development platform. At its roots, the RedBoard is essentially a small portable computer. It is capable of taking **inputs** (such as the push of a button or a reading from a light sensor) and interpreting that information to control various **outputs** (like a blinking LED light or an electric motor).

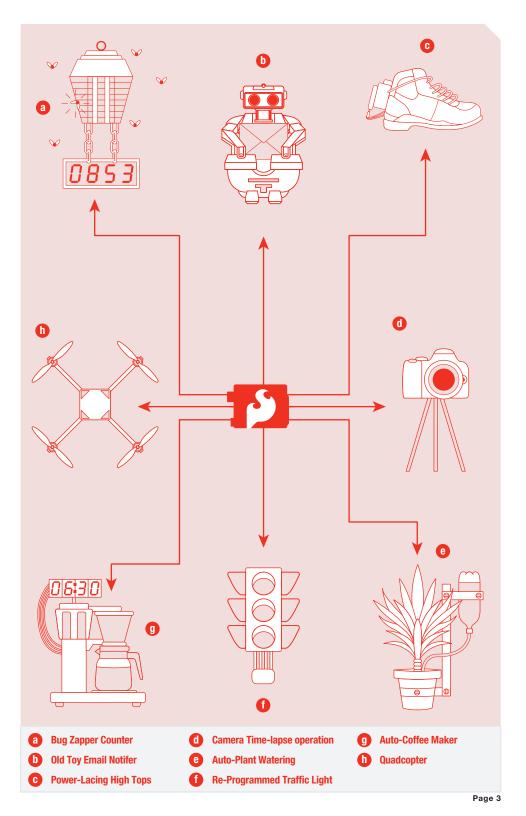
That's where the term "physical computing" is born this board is capable of taking the world of electronics and relating it to the physical world in a real and tangible way. Trust us - this will all make more sense soon.



#### // SparkFun RedBoard

The SparkFun RedBoard is one of a multitude of development boards based on the ATmega328. It has 14 digital input/output pins (6 of which can be PWM outputs), 6 analog inputs, a 16 MHz crystal oscillator, a USB connection, a power jack, an ISP header, and a reset button. Don't worry, you'll learn about all these later.



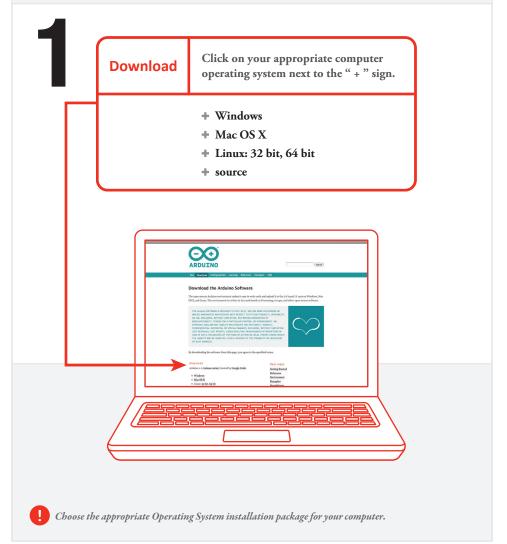




### Access the Internet

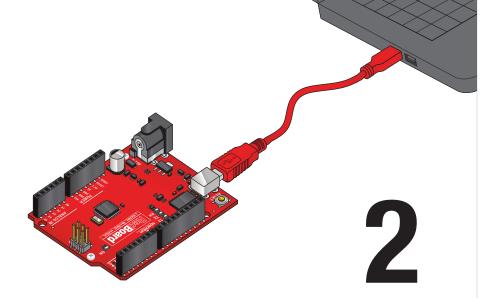
In order to get your RedBoard up and running, you'll need to download the newest version of the Arduino software first from www.arduino.cc (it's free!). This software, known as the Arduino IDE, will allow you to program the board to do exactly what you want. It's like a word processor for writing programs. With an internet-capable computer, open up your favorite browser and type in the following URL into the address bar:





### // Connect your RedBoard to your Computer

Use the USB cable provided in the SIK kit to connect the RedBoard to one of your computer's USB inputs.





# // Install Arduino Drivers

Depending on your computer's operating system, you will need to follow specific instructions. Please go to **www.sparkfun.com/FTDI** for specific instructions on how to install the FTDI drivers onto your RedBoard.



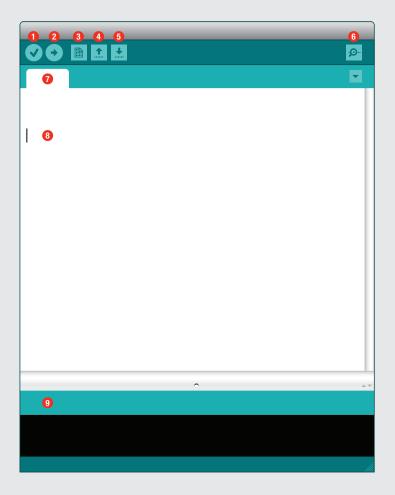






# // Open the Arduino IDE:

Open the Arduino IDE software on your computer. Poke around and get to know the interface. We aren't going to code right away, this is just an introduction. This step is to set your IDE to identify your RedBoard.





4

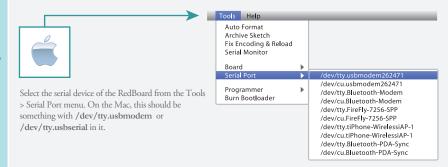
### // Select your board: Arduino Uno

| File Edit Sketch Tools Help  |   |
|--|---|
| Auto Format<br>Archive Sketch<br>Fix Encoding & Re<br>Serial Monitor   | load  |
| Board  | Arduino Uno   |
| Serial Port<br>Programmer<br>Burn Bootloader   | <ul> <li>Arduino Duemilanove w/ ATmega328]</li> <li>Arduino Diecimila or Duemilanove w/ ATmega168</li> <li>Arduino Nano w/ ATmega328</li> <li>Arduino Nano w/ ATmega168</li> <li>Arduino Mega 2560 or Mega ADK</li> <li>Arduino Mega (ATmega1280)</li> </ul>  |
| Note:<br>Your SparkFun RedBoard and the<br>Arduino UNO are interchangeable<br>out you won't find the RedBoard<br>isted in the Arduino Software.<br>Select "Arduino UNO" instead. | Arduino Mini<br>Arduino Mini<br>Arduino Mini<br>Arduino Ethernet<br>Arduino BT w/ ATmega168<br>Arduino BT w/ ATmega168<br>LilyPad Arduino w/ ATmega168<br>Arduino Pro or Pro Mini (SV, 16 MHz) w/ATmega168<br>Arduino Pro or Pro Mini (SV, 16 MHz) w/ATmega168<br>Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ATmega168<br>Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ATmega168<br>Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ATmega168<br>Arduino NG or older w/ ATmega168<br>Arduino NG or older w/ ATmega168 |



Select the serial device of the RedBoard from the Tools | Serial Port menu. This is likely to be **com3 or higher** (COM1 and COM2 are usually reserved for hardware serial ports). To find out, you can disconnect your RedBoard and re-open the menu; the entry that disappears should be the RedBoard. Reconnect the board and select that serial port.

| Tools           | Help   |   |        |
|-----------------|--|---|--------|
| Archi<br>Fix Er | Format<br>ve Sketch<br>ncoding & Reload<br>Monitor |   |        |
|                 | -  |   |        |
| Seria           | Port   |   | com 1  |
|                 | ammer<br>Boot <b>l</b> oader                       | Þ | com 12 |





Download Arduino Code (For use with the circuits in this guide)





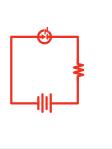
Type in the following URL to download the code:

# sparkfun.com/sikcode



WHAT'S NEXT? Read on to learn more about getting started with circuits. Then you can start on your first circuit on page 17!

### **Getting Started with Circuits**



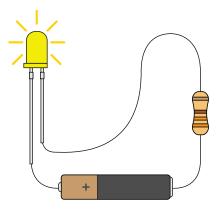
### What is an Electrical Circuit?

A circuit is basically an electrical loop with a starting point and an ending point - with any number of components in between. Circuits can include resistors, diodes, inductors, sensors of all sizes and shapes, motors, and any other handful of hundreds of thousands of components.

Circuits are usually divided into three categories - analog circuits, digital circuits, or mixed-signal circuits. In this guide, you will explore all three sets of circuits.

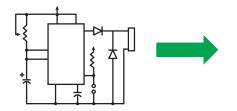
### The World Runs on Circuits:

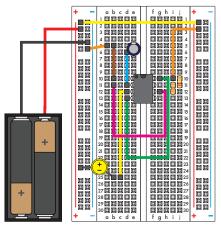
Everywhere you look, you'll find circuits. The cell phone in your pocket, the computer that controls your car's emissions system, your video game console - all these things are chock full of circuits. In this guide, you'll experiment with some simple circuits and learn the gist of the world of embedded electronics.

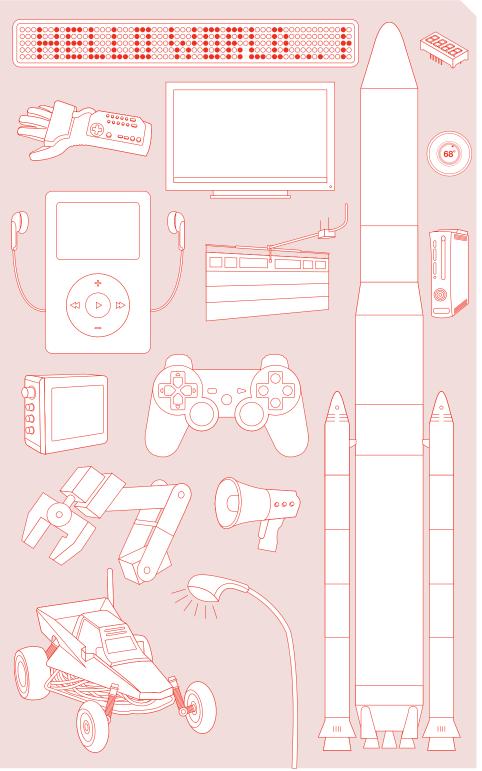


#### // Simple and Complex Circuits

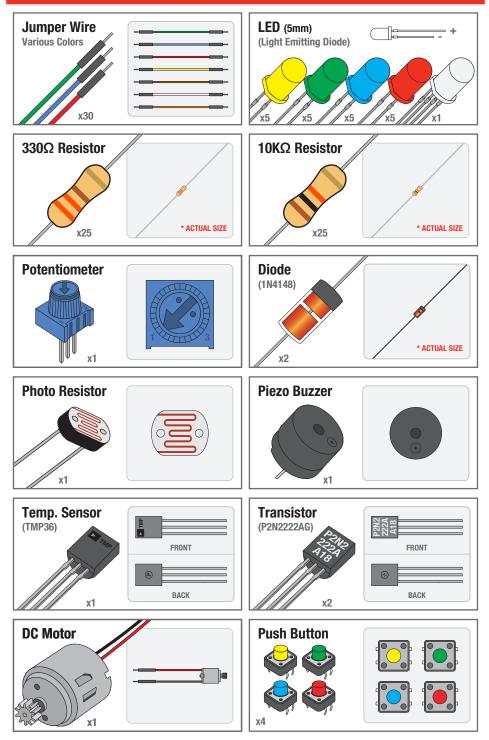
In this guide, you will be primarily exploring simple circuits - but that doesn't mean you can't do amazing things with simple tools! When you've finished the SIK, your knowledge of circuits will enable you to explore amazing projects and unleash the power of your imagination.

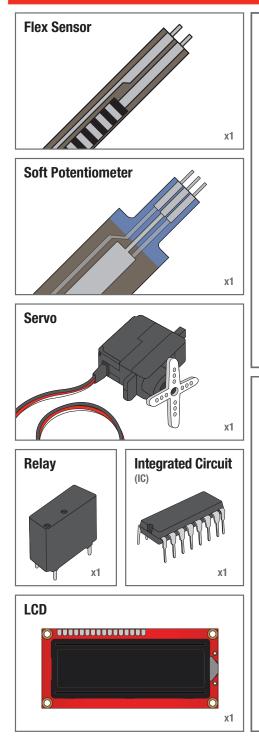


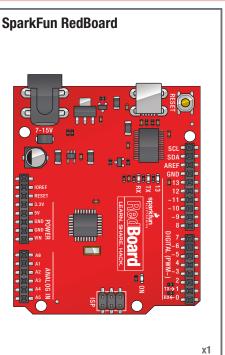




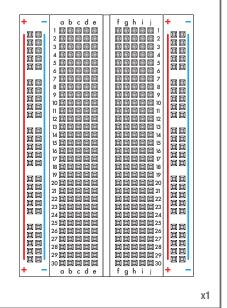
# **Inventory of Parts**

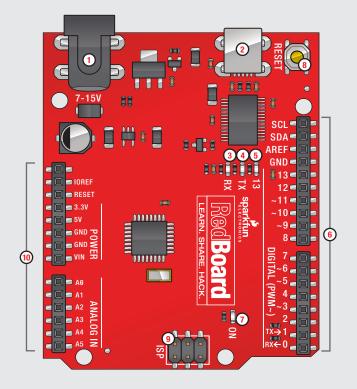


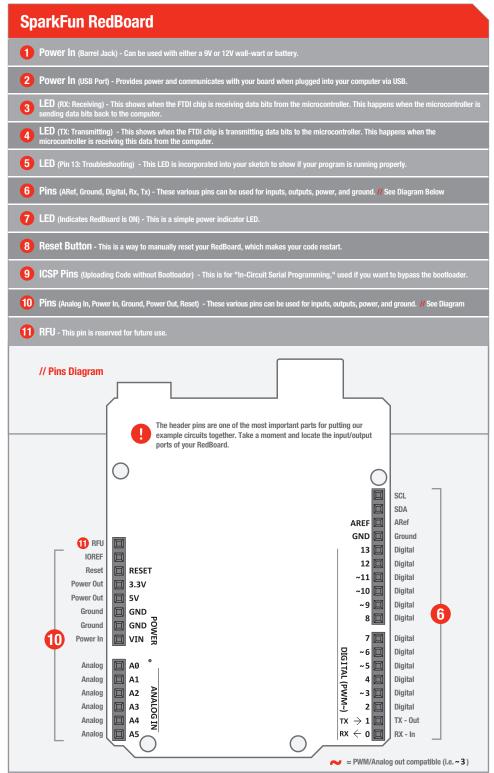


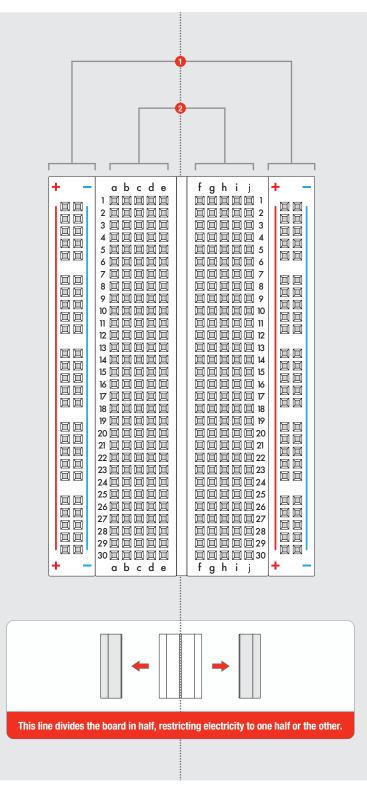


Breadboard Standard Solderless (Color may vary)

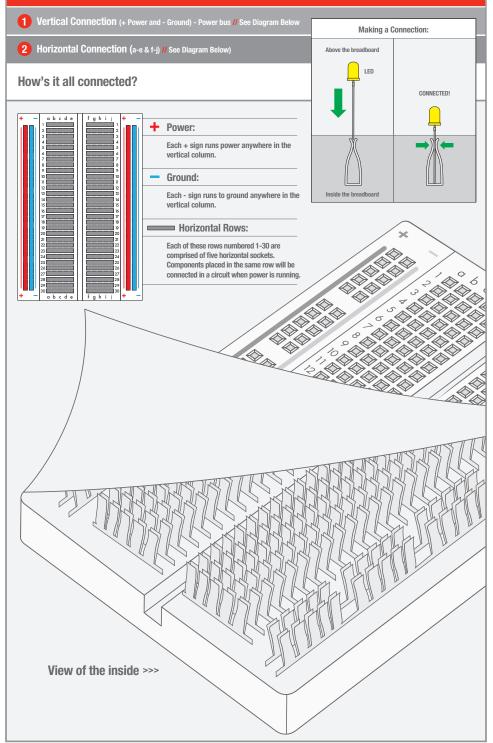




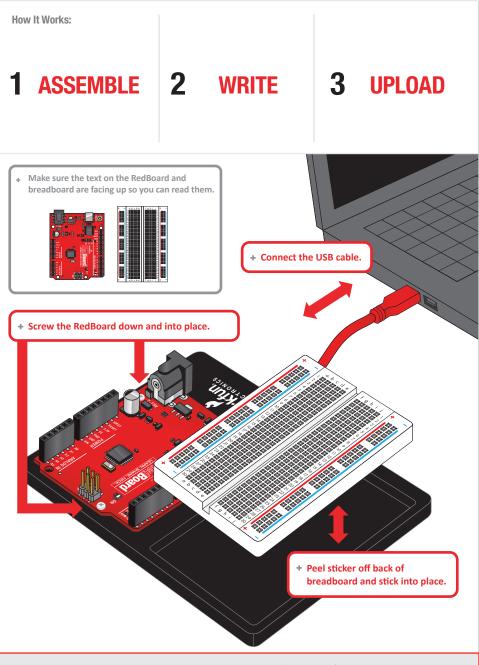




### **Breadboard**

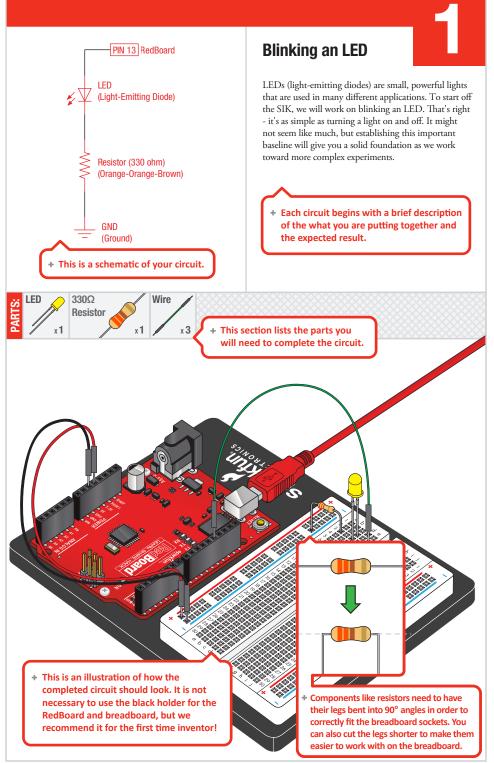


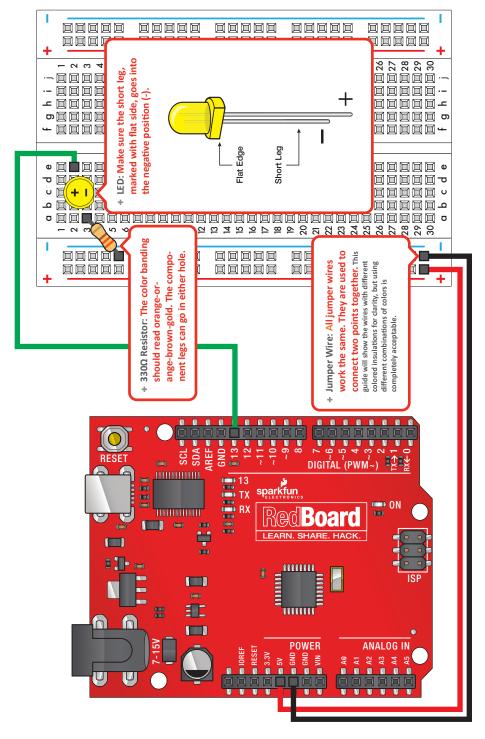
# **CIRCUIT #1 - Your First Circuit**





Your RedBoard runs on 5V. This is the power that will be supplied from your computer via USB and will be the driving force behind any components you use in your circuits. By plugging your RedBoard into your computer, you are supplying it with just the right voltage it needs to thrive! 5V can't hurt you, so don't be afraid to touch anything in your circuit. You can also power the RedBoard through the barrel jack. The on-board voltage regulator can handle anything from 7 to 15VDC.





| Components like LEDs are inserted into the breadboard sockets c2(long leg) c3(short leg). Steps | ingringmee with a yenow warming triangle represent a polarized component. Pay special attention to<br>the component's markings indicating how to place it on the breadboard. | <ul> <li>Resistors are placed in breadboard sockets only. The "." symbol represents any socket in its vertical<br/>column on the Power bus.</li> </ul> | + "GND" on the RedBoard should be connected to the row marked "" on the breadboard. | + "5V" on the RedBoard connects to the row marked "+" on the breadboard. | + "Pin 13" on the RedBoard connects to socket "e2" on the breadboard. | <ul> <li>Breadboard: The white background<br/>represents a connection to a<br/>breadboard socket specified by a<br/>breadboard socket specified by a<br/>letter-number coordinates are merely<br/>suggestions that align with the<br/>graphic image.</li> </ul> |
|---|--|--|---|--|---|---|
|   | c2   c3<br>+   |  |   | +  | e2  | + Breadt<br>repress<br>breadt<br>e.2. The<br>sugges<br>graphic  |
| Image Reference:  | +  |  | GND   | SV   | Pin 13  | * RedBoard: The red background<br>represents a connection to one of<br>the RedBoard header pins.  |
| Component:  | LED (5mm)  | 330Ω Resistor  | Jumper Wire   | Jumper Wire  | Jumper Wire   |   |



### **Open Your First Sketch:**

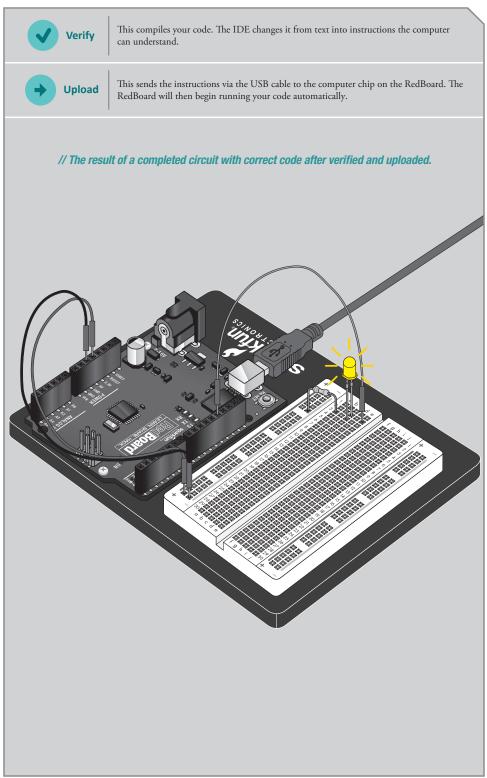
Open Up the Arduino IDE software on your computer. Coding in the Arduino language will control your circuit. Open the code for Circuit 1 by accessing the "SIK Guide Code" you downloaded and placed into your "Examples" folder earlier.

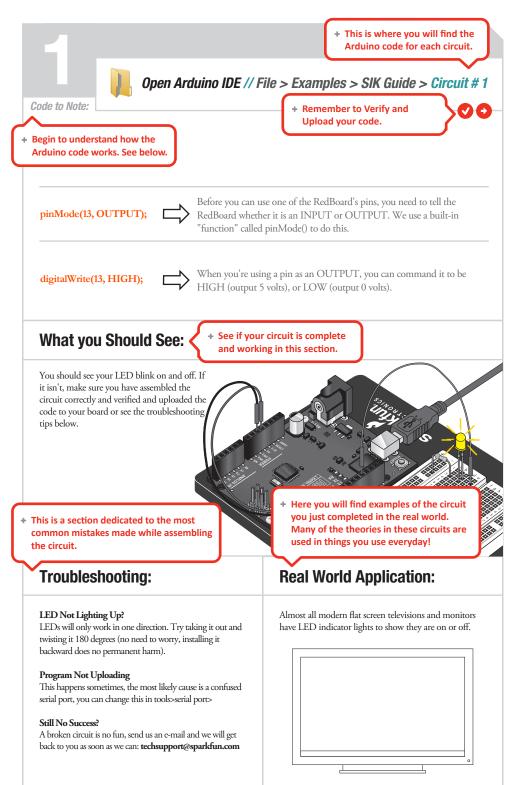
| File Edit Sketch Tools | Help            |             |  |
|------------------------|-----------------|-------------|--|
| New                    |                 |             |  |
| Open<br>Sketchbook     |                 |             |  |
| Examples               | 1.Basics        | )           |  |
| Close                  | 2.Digital       |             |  |
| Save                   | 3.Analog        |             |  |
| Save As                | 4.Communication |             |  |
| Upload                 | 5.Control       |             |  |
| Upload Using Progammer | 6.Sensors       |             |  |
| , 3, 3, 4              | 7.Displays      |             |  |
| Page Setup             | 8.Strings       |             |  |
| Print                  | ArduinoISP      |             |  |
|                        | SIK Guide Code  | Circuit #1  |  |
|                        |                 | Circuit #2  |  |
|                        | EEPROM          | Circuit #3  |  |
|                        | Ethernet        | Circuit #4  |  |
|                        | Firmata         | Circuit #5  |  |
|                        | Liquid Crystal  | Circuit #6  |  |
|                        | SD              | Circuit #7  |  |
|                        | Servo           | Circuit #8  |  |
|                        | SoftwareSerial  | Circuit #9  |  |
|                        | SPI             | Circuit #10 |  |
|                        | Stepper         | Circuit #11 |  |
|                        | Wire            | Circuit #12 |  |
|                        |                 | Circuit #13 |  |
|                        |                 | Circuit #14 |  |
|                        |                 | Circuit #15 |  |
|                        |                 | Circuit #16 |  |

// Circuit #1

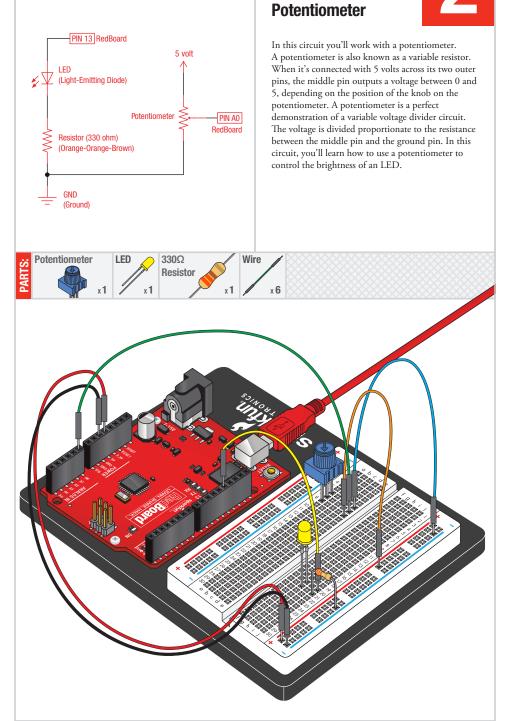
|  | <del>.</del> @- |
|--|-----------------|
| Circuit #1   |                 |
| /*<br>Blink<br>Turns on an LED on for one second,<br>then off for one second, repeatedly.  |                 |
| This example code is in the public domain.   |                 |
| */   |                 |
| <pre>void setup() {     // initialize the digital pin as an output.     // Fin 13 has an LED connected on most ardwino     pintode(13, OUTPUT); }</pre>  | boards:         |
| <pre>void loop() {     digitalWrite(13, HIGH); // set the LED on     delay(1000); // wait for a second     digitalWrite(13, LOW); // set the LED off     delay(1000); // wait for a second }</pre> |                 |
|  |                 |
| <u>^</u>   |                 |
|  |                 |
|  |                 |

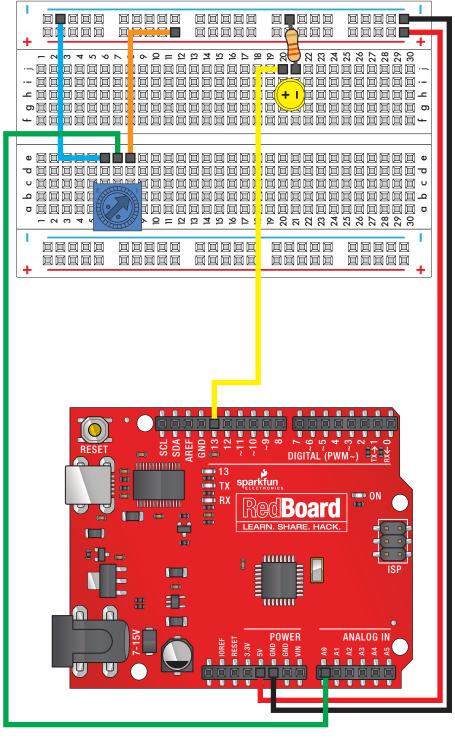
Ł





# CIRCUIT #2





Circuit 2: Potentiometer

| Digital versus Analog: | If you look closely at your RedBoard, you'll see some pins labeled "DIGITAL", | and some labeled ANALOG . What's the difference:<br>Many of the devices you'll interface to, such as LEDs and pushbuttons, have | only two possible states: on and off, or as they're known to the RedBoard,<br>"HIGH" (5 volts) and "LOW" (0 volts). The digital pins on an RedBoard are<br>great at getting these signals to and from the outside world, and can even do | rticks like simulated dimming (by blinking on and off really fast), and serial communications (transferring data to another device by encoding it as patterns of HICH and LOW) |             | DIGITAL LOW of or of on | olts        | But there are also a lot of things out there that aren't just "on" or "off". | Temperature levels, control knobs, etc. all have a continuous range of values<br>between HIGH and LOW. For these situations, the RedBoard offers six analog<br>inputs that translate an input voltase into a number that ranses from 0 (0 volts) | to 1023 (5 volts). The analog pins are perfect for measuring all those "real world" values, and allow you to interface the RedBoard to all kinds of things. | ANALIDE 0 volts to 5 volts | 0  |       |
|------------------------|---|---|--|--|-------------|-------------------------|-------------|--|--|---|----------------------------|----|-------|
|                        | a6<br>a8  | h20 h21   | j21 –  | e6 -   | e7          | e8 +                    | j20         | +  | I  |   | <br>                       |    |       |
|                        |   |   |  |  | AØ          |                         | Pin 13      | ۶۷   | GND  |   |                            |    |       |
| Image Reference:       |   | +   |  |  |             |                         |             |  |  |   |                            |    |       |
| Component:             | Potentiometer   | LED (5mm)   | 330Ω Resistor  | Jumper Wire  | Jumper Wire | Jumper Wire             | Jumper Wire | Jumper Wire  | Jumper Wire  |   |                            | Pa | ge 27 |



Open Arduino IDE // File > Examples > SIK Guide > Circuit # 2

Code to Note:

int sensorValue;

A "variable" is a stored value you've given a name to. You must introduce, or "declare" variables before you use them; here we're declaring a variable called sensorValue, of type "int" (integer). Don't forget that variable names are case-sensitive!

sensorValue = analogRead(sensorPin);

 $\square$ 

We use the analogRead() function to read the value on an analog pin. analogRead() takes one parameter, the analog pin you want to use ("sensorPin"), and returns a number ("sensorValue") between 0 (0 volts) and 1023 (5 volts).

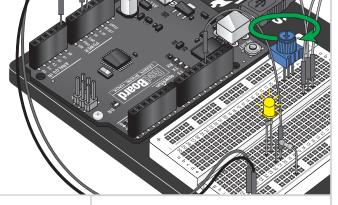
delay(sensorValue);



The Arduino is very very fast, capable of running thousands of lines of code each second. To slow it down so that we can see what it's doing, we'll often insert delays into the code. delay() counts in milliseconds; there are 1000 ms in one second.

### What you Should See:

You should see the LED blink faster or slower in accordance with your potentiometer. If it isn't working, make sure you have assembled the circuit correctly and verified and uploaded the code to your board or see the troubleshooting tips below.



### Troubleshooting:

#### Sporadically Working

This is most likely due to a slightly dodgy connection with the potentiometer's pins. This can usually be conquered by holding the potentiometer down.

#### Not Working

Make sure you haven't accidentally connected the wiper, the resistive element in the potentiometer, to digital pin 0 rather than analog pin 0. (the row of pins beneath the power pins).

#### LED Not Lighting Up?

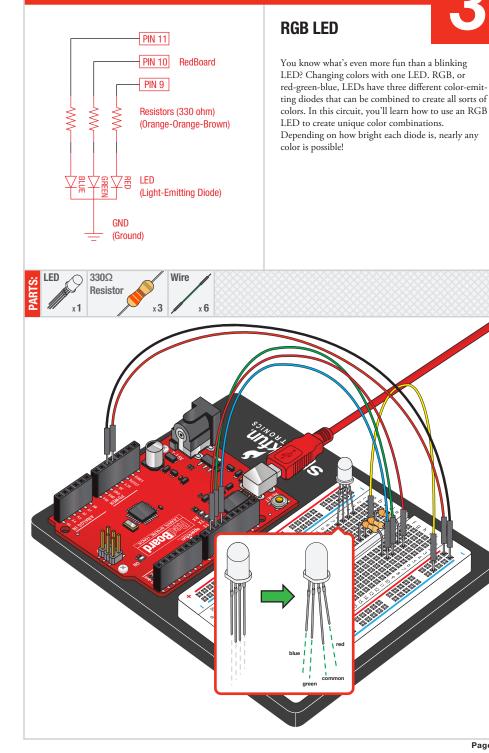
LEDs will only work in one direction. Try taking it out and twisting it 180 degrees (no need to worry, installing it backward does no permanent harm).

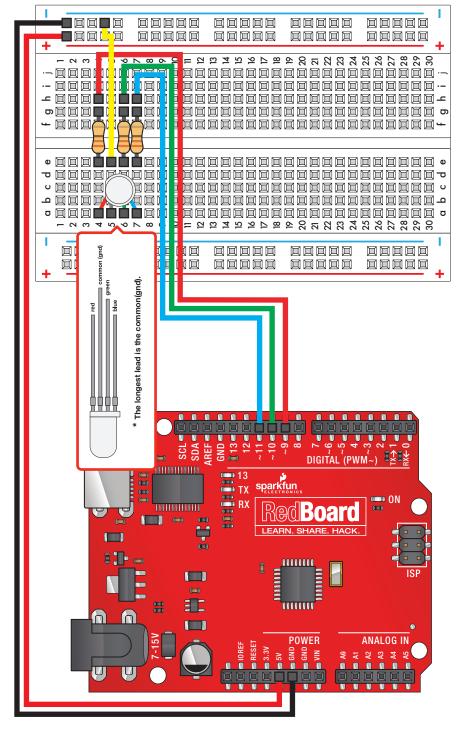
# **Real World Application:**

Most traditional volume knobs employ a potentiometer.



# **CIRCUIT #3**





Circuit 3: RGB LED

| Component:    | Image Reference: |           | The shocking truth behind analogWrite():  |
|---------------|------------------|-----------|---|
| RGB LED (5mm) |                  |           | We've seen that the Arduino can read analog voltages (voltages between 0 and 5 volts) using the <b>analogRead</b> () function. Is there a way for the RedBoard to   |
| 330Ω Resistor |                  | e4 84     | output analog voltages as well?<br>The memories and not The DodBoard does not have a memory of the median   |
| 330Ω Resistor |                  | eó Bo     | output. But, because the RedBoard is so fast, it can fake it using something called <b>PWM</b> ("Pulse-Width Modulation"). The pins on the RedBoard with  |
| 330Ω Resistor |                  | e7 g7     | مبت " mext to them are PWM/Analog out compatible.<br>The RedBoard is so fast that it can blink a pin on and off almost 1000 times   |
| Jumper Wire   |                  | Pin 9     | per second. PWM goes one step further by varying the amount of time that<br>the blinking pin spends HIGH vs. the time it spends LOW. If it spends most<br>of ite time HIGH a 1 FD connected to that non will annear brieht. If it |
| Jumper Wire   |                  | e5 -      | spends most of its time LOW, the LED will look dim. Because the pin is<br>blinking much faster than your eye can detect, the RedBoard creates the   |
| Jumper Wire   |                  | Pin 10 h6 |   |
| Jumper Wire   |                  | Pin 11 h7 | HIGH (5 volts) $\rightarrow$ 90% 0.5V   |
| Jumper Wire   |                  | +         | 10%   |
| Jumper Wire   |                  | - GND     | HIGH (5 volts) → 50% 2.5V   |
|               |                  |           | 50% · · · · · · · · · · · · · · · · · · ·   |
|               |                  |           | HIGH (5 volts) $\rightarrow$ 10%  |
| Page          |                  |           | LOW (0 volts) → 4.5V  |
| 31            |                  |           |   |





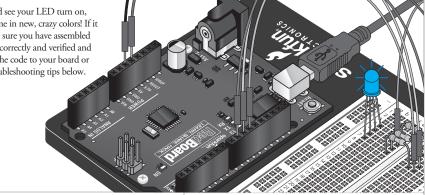
Open Arduino IDE // File > Examples > SIK Guide > Circuit # 3

Code to Note:

| for (x = 0; x < 768; x++)<br>{}   | $\Rightarrow$ | A for() loop is used to step a number across a range, and repeatedly runs code within the brackets {}. Here the variable "x" starts a 0, ends at 767, and increases by one each time ("x++").  |
|-----------------------------------|---------------|--|
| if (x <= 255)<br>{}<br>else<br>{} |               | "If / else" statements are used to make choices in your programs. The statement<br>within the parenthesis () is evaluated; if it's true, the code within the first brackets {}<br>will run. If it's not true, the code within the second brackets {} will run. |
| delay(sensorValue);               | $\Rightarrow$ | The RedBoard is very very fast, capable of running thousands of lines of code each second. To slow it down so that we can see what it's doing, we'll often insert delays into the code. delay() counts in milliseconds; there are 1000 ms in one second.       |

### What you Should See:

You should see your LED turn on, but this time in new, crazy colors! If it isn't, make sure you have assembled the circuit correctly and verified and uploaded the code to your board or see the troubleshooting tips below.



# **Troubleshooting:**

#### LED Remains Dark or Shows Incorrect Color

With the four pins of the LED so close together, it's sometimes easy to misplace one. Double check each pin is where it should be.

#### Seeing Red

The red diode within the RGB LED may be a bit brighter than the other two. To make your colors more balanced, use a higher Ohm resistor. Or adjust in code.

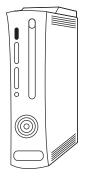
analogWrite(RED\_PIN, redIntensity);

to

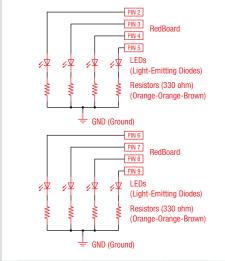
analogWrite(RED\_PIN, redIntensity/3);

# **Real World Application:**

Many electronics such as videogame consoles use RGB LEDs to have the versatility to show different colors in the same area. Often times the diffent colors represent different states of working condition.



### **CIRCUIT #4**



Wire



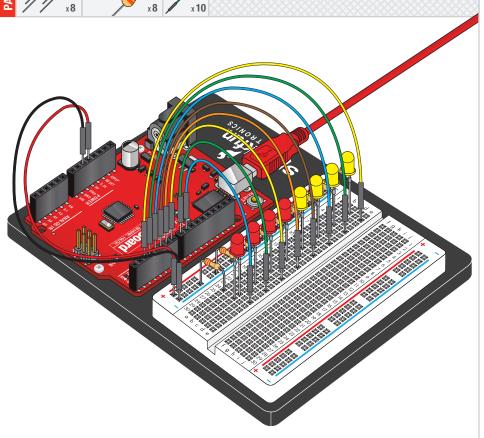
### **Multiple LEDs**

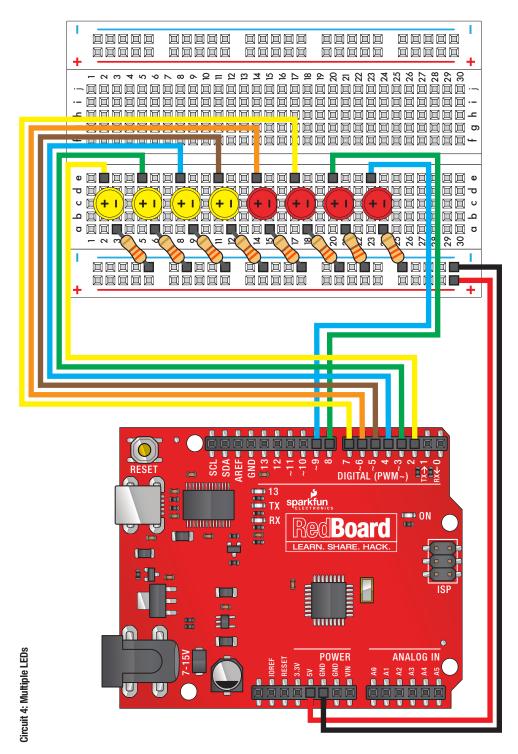
So you have gotten one LED to blink on and off – fantastic! Now it's time to up the stakes a little bit – by connecting EIGHT LEDS AT ONCE. We'll also give our RedBoard a little test by creating various lighting sequences. This circuit is a great setup to start practicing writing your own programs and getting a feel for the way RedBoard works.

Along with controlling the LEDs, you'll learn about a couple programming tricks that keep your code neat and tidy:

for() loops - used when you want to run a piece of code several times

**arrays**[] - used to make managing variables easier by grouping them together





|                  | a18           | a21 <sup>+</sup> - | a24 -         | Pin 2 e2    | Pin 3          | Pin 4 e8    | Pin 5 e11      | Pin 6          | Pin 7         | Pin 8 e20     | Pin 9         | +                    |  |
|------------------|---------------|--------------------|---------------|-------------|----------------|-------------|----------------|----------------|---------------|---------------|---------------|----------------------|--|
| Image Reference: |               |                    |               |             |                |             |                |                |               |               |               |                      |  |
| Component:       | 330Ω Resistor | 330Ω Resistor      | 330Ω Resistor | Jumper Wire | Jumper Wire    | Jumper Wire | Jumper Wire    | Jumper Wire    | Jumper Wire   | Jumper Wire   | Jumper Wire   | Jumper Wire          |  |
|                  | c2 c3 + -     | c5 c6              | c8 c9         | c11 c12 + - | c14 c15<br>+ - | c17 c18     | c20 c21<br>+ - | c23 c24<br>+ - | a3 -          | a6 -          |               | a12 <mark>4 -</mark> |  |
| Image Reference: | +             | +                  | +             | +           | +              | +           | +              | +              |               |               |               |                      |  |
| Component:       | LED (5mm)     | LED (5mm)          | LED (5mm)     | LED (5mm)   | LED (5mm)      | LED (5mm)   | LED (5mm)      | LED (5mm)      | 330Ω Resistor | 330Ω Resistor | 330Ω Resistor | 330Ω Resistor        |  |





20

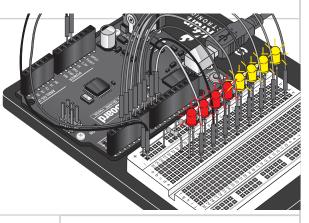
### Open Arduino IDE // File > Examples > SIK Guide > Circuit # 4

Code to Note:

| int ledPins[] = {2,3,4,5,6,7,8,9}; | $\Box$                          | When you have to manage a lot of variables, an "array" is<br>a handy way to group them together. Here we're creating<br>an array of integers, called ledPins, with eight elements.   |
|------------------------------------|---------------------------------|--|
| digitalWrite(ledPins[0], HIGH);    |                                 | You refer to the elements in an array by their position.<br>The first element is at position 0, the second is at position<br>1, etc. You refer to an element using "ledPins[x]" where x<br>is the position. Here we're making digital pin 2 HIGH,<br>since the array element at position 0 is "2". |
| index = random(8);                 | you want to do<br>random() func | e to do the same things each time they run. But sometimes<br>things randomly, such as simulating the roll of a dice. The<br>tion is a great way to do this.<br><b>hino.cc/en/reference/random</b> for more information.  |

### What you Should See:

This is similar to circuit number one, but instead of one LED, you should see all the LEDs blink. If they aren't, make sure you have assembled the circuit correctly and verified and uploaded the code to your board or see the troubleshooting tips below.



### **Troubleshooting:**

#### Some LEDs Fail to Light

It is easy to insert an LED backwards. Check the LEDs that aren't working and ensure they the right way around.

#### Operating out of sequence

With eight wires it's easy to cross a couple. Double check that the first LED is plugged into pin 2 and each pin there after.

#### Starting Afresh

Its easy to accidentally misplace a wire without noticing. Pulling everything out and starting with a fresh slate is often easier than trying to track down the problem.

### **Real World Application:**

Scrolling marquee displays are generally used to spread short segments of important information. They are built out of many LEDs.



### **CIRCUIT #5**

PIN 13 RedBoard

(Light-Emitting Diode)

Resistors (330 ohm)

(Orange-Orange-Brown)

✓ LED ✓ Light

GND

PIN 3

5 volt

PIN 2

Buttons

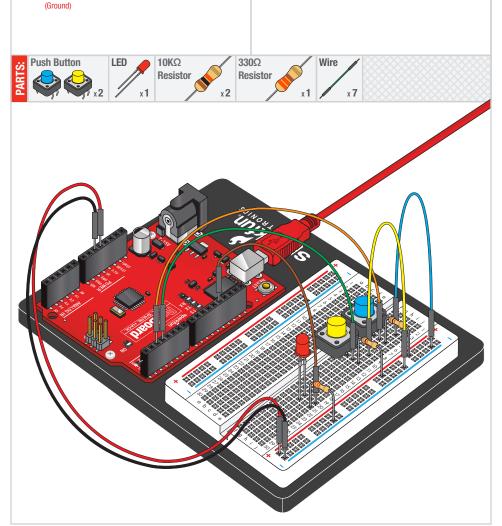
Resistors (10K ohm)

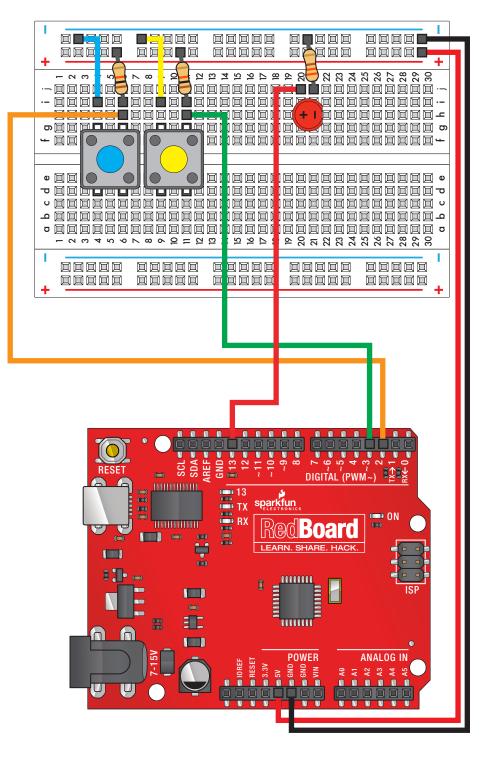
(Brown-Black-Orange)





Up until now, we've focused solely on outputs. Now we're going to go to the other end of spectrum and play around with inputs. In this circuit, we'll be looking at one of the most common and simple inputs – a push button. The way a push button works with RedBoard is that when the button is pushed, the voltage goes LOW. The RedBoard reads this and reacts accordingly. In this circuit, you will also use a pull-up resistor, which keeps the voltage HIGH when you're not pressing the button.





| an:                             | One of the things that makes the RedBoard so useful is that it can make complex decisions<br>based on the innut it's earthine. For example, you could make a thermostar that turns on a | oasee on are mport as security or example, you count make a treatmosta tract and the back of the factor of the<br>heater if it gets too cold, a fan if it gets too hot, waters your plants if they get too dry, etc.<br>In order to make such decisions, the Ardhino environment movides a set of lovic onerations | ns. They include:   | A == B is true if A and B are the SAME. | A I= B is true if A and B are NOT THE SAME. | A && B is true if BOTH A and B are TRUE. | A II B is true if A or B or BOTH are TRUE. | IA IS TRUE IT A IS FALSE<br>IA IS FALSE IF A IS TRUE |             | ia comptex nU statements.   | < threshold)    (override == true)))  |             | turn on a manual override. Using these logic operators, you can program your RedBoard to make intelligent decisions and take control of the world around it! |          |
|---------------------------------|---|--|---|---|---|--|--|--|-------------|---|---|-------------|--|----------|
| How to use logic like a Vulcan: | One of the things that makes the RedB<br>based on the innur it's certino Fore even  | been on an or of the report of a fan if it gets t<br>heater if it gets too cold, a fan if it gets t<br>In order to make such derisions, the Ar   | that let you build complex "if" statements. They include: | == EQUIVALENCE                          | != DIFFERENCE                               | && AND                                   | 8  | ! NOT  | N           | rou can combine trese functions to build complex it/) statements.<br>For example: | if ((mode == heat) && (temperature < threshold)    (override == true))) { dioiteNVVrite(HFATER HICH). | <pre></pre> | turn on a manual override. Using these logic operators, you can primake intelligent decisions and take control of the world around it!                       |          |
|                                 | d4 g4 d6 g6   | d9 g9 d1 g11 g11   | h20-h21   |   | [11] +                                      |  | j21+ -                                     | - + i  | - <u>6</u>  | Pin 2 h6  | Pin 3 h11   | Pin 13 j20  | +  | -<br>GND |
| Image Reference:                |   |  | +   |   |   |  |  |  |             |   |   |             |  |          |
| Component:                      | Push Button   | Push Button  | LED (5mm)   | 10KΩ Resistor                           | 10KΩ Resistor                               |  | 330Ω Resistor                              | Jumper Wire  | Jumper Wire | Jumper Wire   | Jumper Wire   | Jumper Wire | Jumper Wire  | Page 39  |

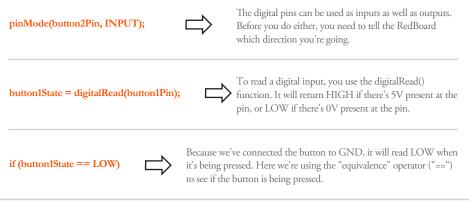




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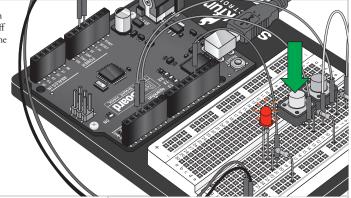
Arduino Code:

Code to Note:



# What You Should See:

You should see the LED turn on if you press either button, and off if you press both buttons. (See the code to find out why!) If it isn't working, make sure you have assembled the circuit correctly and verified and uploaded the code to your board or see the troubleshooting tips below.



# Troubleshooting:

#### Light Not Turning On

The pushbutton is square, and because of this it is easy to put it in the wrong way. Give it a 90 degree twist and see if it starts working.

#### Underwhelmed

No worries, these circuits are all super stripped down to make playing with the components easy, but once you throw them together the sky is the limit.

# **Real World Application:**

The buttons we used here are similar to the buttons in most video game controllers.

